

ROCHESTER INSTITUTE OF TECHNOLOGY COURSE PROPOSAL FORM

COLLEGE OF SCIENCE

Chester F. Carlson Center for Imaging Science

REVISED COURSE: COS-IMGS-682-Image Processing and Computer Vision

1.0 Course Designations and Approvals

| Required course approvals: | Approval request date: | Approval granted date: |
|------------------------------------|------------------------|------------------------|
| Academic Unit Curriculum Committee | 10/8/2014 | 10/8/2014 |
| College Curriculum Committee | | |

| Optional designations: | Is designation desired? | *Approval request date: | **Approval granted date: |
|------------------------|-------------------------|-------------------------|--------------------------|
| General Education: | No | | |
| Writing Intensive: | No | | |
| Honors | No | | |

2.0 Course information:

| Course title: | Image Processing and Computer Vision |
|---------------------|--------------------------------------|
| Credit hours: | 3 |
| Prerequisite(s): | IMGS-616 or permission of instructor |
| Co-requisite(s): | None |
| Course proposed by: | Nathan Cahill |
| Effective date: | October 2014 |

| | Contact hours | Maximum students/section |
|-----------------|---------------|--------------------------|
| Classroom | 3 | 50 |
| Lab | | |
| Studio | | |
| Other (specify) | | |

2.a Semester(s) offered (check)

| | Fall | Spring √ | Summer | Other |
|--|------|----------|--------|-------|
|--|------|----------|--------|-------|

All courses must be offered at least once every 2 years. If course will be offered on a biannual basis, please indicate here:

2.b Student Requirements

Students required to take this course: (by program and year, as appropriate) Graduate students in Imaging Science Ph.D. program

Students who might elect to take the course:

Graduate students in the Imaging Science M.S. program. Nonmatriculated students with undergraduate degrees in the physical sciences or engineering. Graduate students in the College of Science, Kate Gleason College of Engineering, or the B. Thomas Golisano College of Computing and Information Sciences.

In the sections that follow, please use sub-numbering as appropriate (eg. 3.1, 3.2, etc.)

3.0 Goals of the course (including rationale for the course, when appropriate):

This course will provide the students with a firm understanding of the basic concepts of image manipulation and analysis through a mathematical framework and computational implementation. The students will critically examine the current literature with the goal of identifying and implementing current state-of-the-art algorithms in image processing and computer vision in the core topical areas discussed. The students will become adept at documenting their efforts through written technical papers.

4.0 Course description

COS-IMGS-682 Image Processing and Computer Vision

This course will cover a wide range of current topics in modern image processing and computer vision. Topics will include linear and nonlinear systems of equations, point processing, linear and nonlinear filtering, dimensionality reduction, feature matching, image registration, image segmentation and object recognition, and geometry of cameras. Projects will involve advanced computational implementations of selected topics from the current literature in a high level language such as MATLAB or IDL and will be summarized by the students in written technical papers. (COS-IMGS-616 or permission of instructor) Class 3, Credit 3 (S)

5.0 Possible resources (texts, references, computer packages, etc.)

- 5.1 Gonzalez, R.C. and R.E. Woods, Digital Image Processing, Prentice Hall
- 5.2 Hartley, R. and A. Zisserman, Multiple View Geometry in Computer Vision, Cambridge University Press
- 5.3 Szeliski, R., Computer Vision: Algorithms and Applications, Springer
- 5.4 MATLABTM (MathWorks) or IDLTM (ITT Visual Information Solutions)
- 5.5 Numerous articles available in the current published literature

6.0 Topics (outline):

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6.1 Linear Systems of Equations

- 6.1.1 Vector spaces and subspaces
- 6.1.2 Fundamental subspaces of a matrix
- 6.1.3 Solving Ax = b
 - 6.1.3.1 Square, full-rank systems
 - 6.1.3.2 Overdetermined systems, least squares
- 6.1.4 Eigenvectors and diagonalization
- 6.1.5 Singular value decomposition
- 6.1.6 Circulant matrices and the Discrete Fourier Transform
- 6.2 Nonlinear Systems of Equations
 - 6.2.1 Linearization
 - 6.2.2 Gauss-Newton
 - 6.2.3 Levenberg-Marquardt
- 6.3 Point Processing
 - 6.3.1 Dynamic range adjustment
 - 6.3.2 Color transformations
 - 6.3.3 Histogram equalization
- 6.4 Filtering
 - 6.4.1 Review of Linear Filtering
 - 6.4.1.1 Sampling Theory, DFT, FFT
 - 6.4.1.2 Kernel size, border effects, filter separability
 - 6.4.1.2 Image deconvolution, phase retrieval, and matched filtering
 - 6.4.2.4 Wiener filter
 - 6.4.2 Nonlinear Filtering
 - 6.4.2.1 Statistical filters
 - 6.4.2.2 Morphological filters
 - 6.4.2.3 Bilateral filter
 - 6.4.2.4 Nonlocal means filter
 - 6.4.2.5 Total variation filter
- 6.5 Dimensionality Reduction
 - 6.5.1 Principal component analysis
 - 6.5.2 Nonlinear manifold learning
 - 6.5.2 Image compression
- 6.6 Feature Matching
 - 6.6.1 Corner detectors (Harris)
 - 6.6.2 Descriptive features (SIFT, SURF, HoG)
 - 6.6.3 Robust matching (RANSAC)
- 6.7 Image Registration
 - 6.7.1 Rigid/affine registration
 - 6.7.2 Nonrigid registration
 - 6.7.2.1 BSpline free-form deformations
 - 6.7.2.2 Variational models
 - 6.7.3 Multimodality registration
- 6.8 Image Segmentation
 - 6.8.1 Parametric models and snakes
 - 6.8.2 Level sets

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- 6.8.3 Markov random fields and graph cuts
- 6.8.4 Bayesian networks and image understanding
- 6.9 Geometry of Cameras
 - 6.9.1 Single-view geometry, perspective projection
 - 6.9.2 Homography
 - 6.9.3 Multiple-view geometry
 - 6.9.3.1 Fundamental matrix
 - 6.9.3.2 Bundle adjustment

7.0 Intended course learning outcomes and associated assessment methods of those outcomes (please include as many Course Learning Outcomes as appropriate, one outcome and assessment method per row).

| appropriate, one outcome and assessment method per ro | · · · · · · · · · · · · · · · · · · · |
|--|---------------------------------------|
| Course Learning Outcome | Assessment Method |
| 7.1 Demonstrate a theoretical understanding of image | Examination / In-class |
| processing and computer vision methods and how they fit | Attendance |
| into the imaging chain | |
| 7.2 Demonstrate a fluency and aptitude for implementing | Homework and Projects |
| image processing and computer vision algorithms found in | |
| the literature | |
| 7.3 Demonstrate an ability to communicate the details of | Homework and Projects |
| image processing and computer vision methods, | |
| implementations, results, and analysis in written media | |

8.0 Program outcomes and/or goals supported by this course

This course will provide a working knowledge of image processing and computer vision techniques to solve problems in the physical sciences or engineering.

9.0

| | General Education Learning Outcome Supported by the Course, if appropriate | Assessment Method |
|----------------|---|----------------------|
| Communicati | ion | |
| | Express oneself effectively in common college-level written | |
| | forms using standard American English | |
| | Revise and improve written products | |
| | Express oneself effectively in presentations, either in spoken | |
| | standard American English or sign language (American Sign | |
| | Language or English-based Signing) | |
| | Comprehend information accessed through reading and | |
| | discussion | |
| Intellectual I | nquiry | |
| | Review, assess, and draw conclusions about hypotheses and | |
| | theories | |
| | Analyze arguments, in relation to their premises, assumptions, | |
| | contexts, and conclusions | |
| | Construct logical and reasonable arguments that include | |
| | anticipation of counterarguments | |
| | Use relevant evidence gathered through accepted scholarly | |
| | methods and properly acknowledge sources of information | |

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| Ethical, Soci | al and Global Awareness |
|----------------|---|
| | Analyze similarities and differences in human experiences and |
| | consequent perspectives |
| | Examine connections among the world's populations |
| | Identify contemporary ethical questions and relevant |
| | stakeholder positions |
| Scientific, M | athematical and Technological Literacy |
| | Demonstrate knowledge of basic principles and concepts of |
| | one of the natural sciences |
| | Apply methods of scientific inquiry and problem solving to |
| | contemporary issues |
| | Comprehend and evaluate mathematical and statistical |
| | information |
| | Perform college-level mathematical operations or apply |
| | statistical techniques |
| | Describe the potential and the limitations of technology |
| | Use appropriate technology to achieve desired outcomes |
| Creativity, In | novation and Artistic Literacy |
| | Demonstrate creative/innovative approaches to course-based |
| | assignments or projects |
| | Interpret and evaluate artistic expression considering the |
| | cultural context in which it was created |

10.0 Other relevant information (such as special classroom, studio, or lab needs, special scheduling, media requirements, etc.) 10.1 Classroom with in-class presentation system

10.2 Classroom with distance learning computing and audio/video system

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